

Log-signatures and Neural Rough Differential Equations

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DataSig and Oxford



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A rough path between
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Outline

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Signatures and Log-signatures

As we've already seen, the *signature* is a collection of features $\text{Sig}_{a,b}(X)$ that we define from a continuous path $X : [0, T] \rightarrow \mathbb{R}^d$ (of finite length).

Definition (Depth- N Signature)

The depth- N signature transform of X over the interval $[a, b]$ is given by

$$\text{Sig}_{a,b}^N(X) = \left(\{S_{a,b}^i(X)\}_{i=1}^d, \{S_{a,b}^{i,j}(X)\}_{i,j=1}^d, \dots, \{S_{a,b}^{i_1, \dots, i_N}(X)\}_{i_1, \dots, i_N=1}^d \right) \quad (1)$$

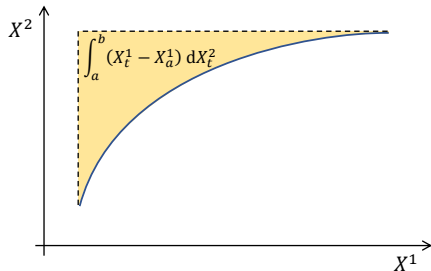
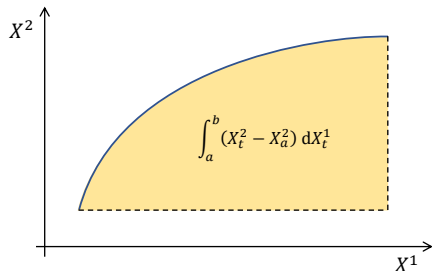
where

$$S_{a,b}^{i_1, \dots, i_k}(X) = \int_{a < t_1 < t_2 < \dots < t_k < b} \dots \int dx_{t_1}^{i_1} dx_{t_2}^{i_2} \dots dx_{t_k}^{i_k}.$$

Is there redundancy in this feature set? If so, how can it be compressed?

Signatures and Log-signatures

Already with $d = 2$ and $N = 2$, we can see there is some redundancy



as a simple application of integration by parts yields

$$\iint_{a < t_1 < t_2 < b} dX_{t_1}^1 dX_{t_2}^2 + \iint_{a < t_1 < t_2 < b} dX_{t_1}^2 dX_{t_2}^1 = (X_b^1 - X_a^1)(X_b^2 - X_a^2).$$

Signatures and Log-signatures

Definition (Depth-2 Log-signature)

The depth-2 log-signature transform of X is given by

$$\text{LogSig}_{a,b}^2(X) = \left(\{X_b^i - X_a^i\}_{1 \leq i \leq d}, \right. \\ \left. \left\{ \frac{1}{2} \left(\iint_{a < t_1 < t_2 < b} dX_{t_1}^i dX_{t_2}^j - \iint_{a < t_1 < t_2 < b} dX_{t_1}^j dX_{t_2}^i \right) \right\}_{1 \leq i < j \leq d} \right) \quad (2)$$

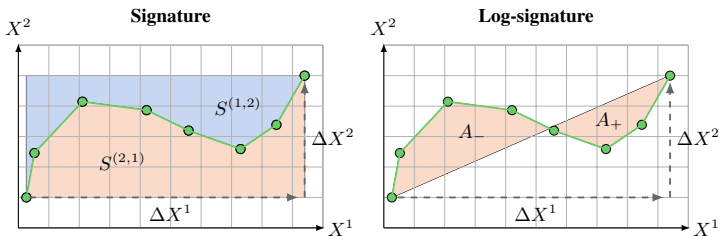





Figure: Illustration of depth-2 signature and log-signature (taken from [1]).

Signatures and Log-signatures

Removing redundancy at depth-3 gives log-signature terms of the form:

$$\frac{1}{6} \iiint_{a < t_1 < t_2 < t_3 < b} \left(dX_{t_1}^i (dX_{t_2}^j dX_{t_3}^k - dX_{t_2}^k dX_{t_3}^j) - (dX_{t_1}^j dX_{t_2}^k - dX_{t_1}^k dX_{t_2}^j) dX_{t_3}^i \right).$$

Log-signatures have an interesting computational and algebraic story!

-  P. Kidger and T. Lyons. *Signatory: differentiable computations of the signature and logsignature transforms, on both CPU and GPU*. In International Conference on Learning Representations, 2021. <https://github.com/patrick-kidger/signatory>
-  J. Diehl, T. Lyons, R. Preiß and J. Reizenstein. *Areas of areas generate the shuffle algebra*. arXiv:2002.02338, 2020.
-  J. Reizenstein. *Calculation of Iterated-Integral Signatures and Log Signatures*. arXiv:1712.02757, 2017.

Log-signatures as a method for lossy compression

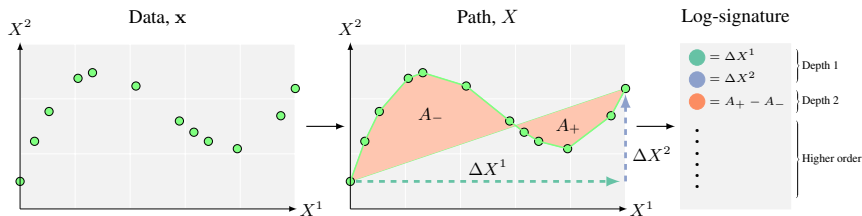


Figure: Illustration of depth-2 log-signature (taken from [6]).

We can reduce the length of a time series by computing log-signatures (locally) over different intervals. This gives a length/channel trade-off.

Using log-signatures as a preprocessing step can improve performance for ML models such as RNNs [1, 5] and neural differential equations [6].

We focus on the latter, which we call *Neural Rough Differential Equations*

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Neural Controlled Differential Equations (NCDEs)

We observe $\mathbf{x} = ((t_0, x_0), (t_1, x_1), \dots, (t_n, x_n))$, with $t_i \in \mathbb{R}$ and $x_i \in \mathbb{R}^d$.

Let $X : [0, n] \rightarrow \mathbb{R}^{d+1}$ be a continuous path that interpolates this data, so $X(i) = (t_i, x_i)$. (e.g. cubic splines [7] and piecewise linear/rectilinear [8])

The NCDE model involves learnt functions ζ_θ, f_θ and a linear map ℓ_θ with

$$z(0) = \zeta_\theta(t_0, x_0), \quad z(t) = z(0) + \int_0^t f_\theta(z(s)) dX(s), \quad (3)$$

and the output is either $\ell_\theta(z(T))$ or $\{\ell_\theta(z(t))\}$.

The CDE model (3) is discretized, the output is fed into a loss function (L^2 , cross entropy, etc) and trained using stochastic gradient descent.

Here ζ_θ and f_θ are neural nets, z is hidden state: [Continuous Time RNN](#)

Neural Controlled Differential Equations (NCDEs)

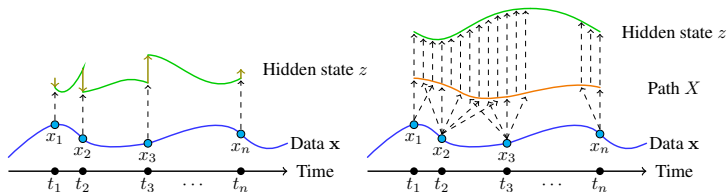


Figure: Illustration of the RNN and NCDE models (taken from [7]).

What does rough path theory tell us about log-signatures / CDEs?

CDE solution \approx Truncated Taylor expansion of CDE solution
= Linear functional applied to $\text{Sig}^N(X)$
= Linear functional applied to exponential of $\text{LogSig}^N(X)$
 \approx Exponential of linear functional applied to $\text{LogSig}^N(X)$
= Solving an ODE obtained from f_θ and $\text{LogSig}^N(X)$

Conclusion

Log-signatures and Neural CDEs are a natural fit!

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Neural Rough Differential Equations (NRDEs)

Definition (Neural RDE)

We pick a (uniform) partition $\{r_i\}$ of $[t_0, t_n]$ and depth hyperparameter N . The Neural RDE model follows the Neural CDE formulation, but with

$$z(t) = z(0) + \int_0^t g_{\theta, X}(z(s), s) ds, \quad (4)$$

where $g_{\theta, X}(z, s) = \hat{f}_{\theta}(z) \frac{\text{LogSig}_{r_i, r_{i+1}}^N(X)}{r_{i+1} - r_i}$, for $s \in [r_i, r_{i+1})$.

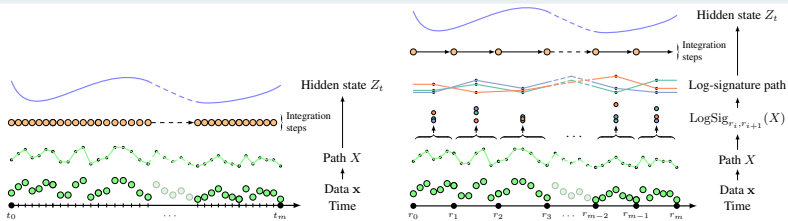


Figure: Illustration of the NCDE and NRDE models (taken from [6]).

Classification on time series with a length of 17K

Model	Step	Accuracy (%)	Time (Hrs)	Mem (Mb)
	1	–	–	–
ODE-RNN (folded)	4	35.0 ± 1.5	0.8	3629.3
	32	32.5 ± 1.5	0.1	532.2
	128	47.9 ± 5.3	0.0	200.8

NCDE	1	62.4 ± 12.1	22.0	176.5
	4	66.7 ± 11.8	5.5	46.6
	32	64.1 ± 14.3	0.5	8.0
	128	48.7 ± 2.6	0.1	3.9

NRDE (depth 2)	4	83.8 ± 3.0	2.4	180.0
	32	67.5 ± 12.1	0.7	28.1
	128	76.1 ± 5.9	0.2	7.8

NRDE (depth 3)	4	76.9 ± 9.2	2.8	856.8
	32	75.2 ± 3.0	0.6	134.7
	128	68.4 ± 8.2	0.1	53.3

Table: EigenWorms dataset: mean ± standard deviation of test set accuracy measured over three runs. Bold denotes the best score for a given step size.

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Conclusion

- The log-signature is a compressed version of the signature
 - nice geometric interpretation
 - reduces length of a time series, but increases number of channels
 - can improve performance for RNNs [1, 5] and Neural CDEs [6]
- CDEs are naturally related to log-signatures and ODEs (“log-ODE”)
- Neural RDEs combine the strengths of NCDEs and log-signatures
 - memory efficient, continuous time and suitable for long time series
 - when $\text{step} = 1$ and $\text{depth} = 1$, reduces to usual Neural CDE model
- Code available
 - <https://github.com/patrick-kidger/signatory>
 - <https://github.com/patrick-kidger/torchcde>
 - <https://github.com/jambo6/neuralRDEs>

Thank you for your attention!





and for more details, see

-  J. Morrill, C. Salvi, P. Kidger, J. Foster and T. Lyons. *Neural Rough Differential Equations for Long Time Series*. Proceedings of the 38th International Conference on Machine Learning (ICML), 2021.





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References I

-  J. Morrill, A. Fermanian, P. Kidger and T. Lyons. *A Generalised Signature Method for Multivariate Time Series Feature Extraction*. arXiv:2006.00873, 2020.
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